

# Simplified Finite Element Analysis

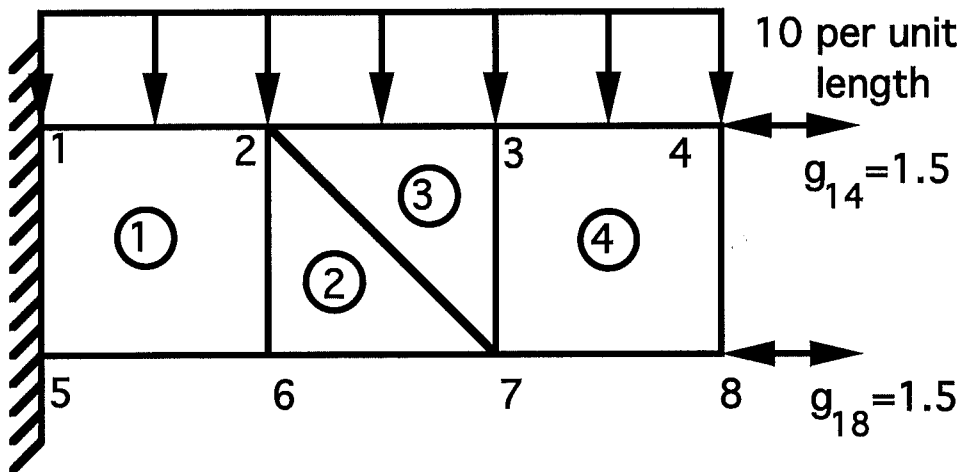
The goal of this write-up is to introduce a structure to demonstrate the basic concepts associated with the calculation of element matrices, assembling them into the global matrices and recovering elemental quantities. The method used to do this uses some simple pseudo code and data structures (sort of). Please note the following assumptions

- all potential dof are associated with node points
- the # of dof per node is the same for all nodes and is equal to  $n_{sd}$

and also consider one alteration from the text

- data structures similar to those in the text will be used with some modifications introduced to make them simpler, slightly more general, and to make it clearer how to handle the prescribed nodal displacements,  $g_{iA}$

## example problem to be considered



## procedure FEA (NNP; NEL; NSD)

{simplistic view of a finite element analysis process}

**var**

NNP = { $n_{np}$ , number of nodes mesh}

NEL = { $n_{el}$ , number of elements mesh}

NSD = { $n_{sd}$ , number of space dimensions}

NDOF = { $n_{dof}$ , number of dof in global matrices (please note this is a  
change from the text in the use of terms)}

NDOG = { $n_{dog}$ , number dof associated with non-zero  $g_{iA}$ 's}

ID = {"destination structure" holds "global equations numbers"  
explained in SETUP\_EQ}

K = { $\mathbf{K}$ , global stiffness matrix ( $n_{dof}, n_{dof}$ )}

F = { $\mathbf{F}$ , global force vector ( $n_{dof}$ )}

G = {global prescribed displacement vector ( $n_{dog}$ )}

NEN = { $n_{en}$ , number of nodes per element}

LM = {element "location matrix" explained in SETUP\_EQ}

KE = { $\mathbf{k}^e$ , element stiffness matrix ( $n_{ee}, n_{ee}$ ), ( $n_{ee} = n_{en} n_{sd}$ )}

FE = { $\mathbf{F}^e$ , element force vector ( $n_{ee}$ )}

DISP = { $\mathbf{d}$ , global displacement vector ( $n_{dof}$ )}

**begin**

**call** SETUP\_EQ (NNP,NEL,NSD,ID,NDOF,NDOG,K,F,G)

{label global equation #'s and initialize global matrices}

**for** I\_EL = 1 **to** NEL {loop over # of elements to calculate  
element matrices}

**call** ELE\_STIFF (NSD,ID,LM,NEN,KE,FE) {calc. element  
stiffness matrix and element location vector}

**call** ASSEMBLE (NSD,LM,NEN,KE,FE,G,K,F)  
{assemble the element matrices into the global matrices}

**end** {for}

**call** SOLVE (NDOF,K,F,DISP) {solve global system ( $\mathbf{d} = \mathbf{K}^{-1}\mathbf{F}$ )}

**call** OUTPUT\_DISP. (NNP,NSD,ID,DISP,G)

{print out the displacements at the nodes}

**for** I\_EL = 1 **to** NEL {calculate and print out stresses or fluxes}

**call** OUT\_FLUX (NSD,ID,DISP,G)

**end** {for}

**end** {FEA}

**procedure** SETUP\_EQ (NNP;NEL;NSD;ID;NDOF;NDOG;K;F;G)

{This procedure is responsible for specifying the equation numbers at each of the possible nodal dof and identifying the essential BC}

**var**

ID = {Destination matrix which, for each possible dof, gives the equation number (if it is an equation) or the location of the prescribed essential BC in G (if the essential BC is specified). Consider ID as an array where each entity is given a type, t.

$$ID(i, A: t) \quad i = 1(1)n_{sd}, \quad A = 1(1)n_{np}, \quad t = \begin{cases} dof & \text{if } i, A \in \eta - \eta_{g_i} \\ dog & \text{if } i, A \in \eta_{g_i} \text{ and } g_{iA} \neq 0 \\ null & \text{if } i, A \in \eta_{g_i} \text{ and } g_{iA} = 0 \end{cases}$$

NTYP = {vector indicating the type of dof for each component at the node.

$$NTYP(i) = \begin{cases} dof & \text{if } NTYP(i) \in \eta - \eta_{g_i} \\ dog & \text{if } NTYP(i) \in \eta_{g_i} \text{ and } g_{iA} \neq 0 \\ null & \text{if } NTYP(i) \in \eta_{g_i} \text{ and } g_{iA} = 0 \end{cases}$$

FG = {vector of either nodal point forces or nodal prescribed essential

$$BC. \quad FG(i) = \begin{cases} load & \text{if } NTYP(i) = dof \\ g_{iA} & \text{if } NTYP(i) = dog \end{cases} \quad \}$$

**begin**

{initialize global counters}

NDOF = 0

NDOG = 0

**for** A = 1 **to** NNP **do** {loop over the nodes setting the equation or prescribed essential BC number and load the global nodal loads or prescribed essential BC}

**read** ((NTYP(i), i= 1, NSD) (FG(i),i=1,NSD)

**for** i = 1 **to** NSD **do**

**if** NTYP(i) = *dof* **then** {the possible dof is a dof}

NDOF = NDOF+1

t = *dof*

ID(i,A:t) = NDOF {give it an equation number}

F(NDOF) = FG(i) {if there are nodal loads}

**else** {the possible dof is a prescribed essential BC}

**if** NTYP(i) = *dog* **then** {nonzero prescribed essential BC}

NDOG = NDOG+1

t = *dog*

ID(i,A:t) = NDOG {pointer to location of value}

G(NDOG) = FG(i) (storing value of essential BC)

**else** {zero prescribed essential BC}

t = *null*

ID(i,A:t) = 0 {allow us to skip zero multiplies}

**end** {if}

**end** {if}

**end** {loop over possible dof at node}

**end** {loop over nodes}

{zero out the global stiffness matrix}

**for** A = 1 **to** NDOF **do**

**for** B = 1 **to** NDOF **do**

K(A,B) = 0.0

**end** {loop over possible dof at node}

**end** {loop over nodes}

**end** {SETUP\_EQ}

**procedure** ELE\_STIFF (NSD, ID, LM, NEN, KE, FE)

{main routine for calculating the element matrices}

**var**

NEN = { $n_{en}$  number of nodes for the element}

IEN = {vector of global node numbers for the nodes defining the element ( $n_{en}$ )}

LM = {element location vector identifying the equation numbers and location of prescribed essential BC for the element ( $n_{sd}, n_{en}:t$ )}

N = {element shape functions ( $n_{en}$ )}

B = {Derivatives of shape functions as defined by the strain-displacement relations, for  $n_{sd} = 2$  it is ( $3, 2n_{en}$ )}

S = {Stress displacement matrix, for  $n_{sd} = 2$  it is ( $3, 2n_{en}$ )}

**begin**

**read** (NEN, (IEN(a), a=1, NEN)) {read in the elements nodes}

{set-up the location vector which will keep track of the mapping between the local dof numbers and the global equation or specified essential BC numbers}

**for** a = 1 **to** NEN **do**

    A = IEN(a)

**for** i = 1 **to** NSD **do**

        LM(i, a:t) = ID(i, A:t)

**end** {do}

**end** {do}

{read element material properties and obtain nodal coordinate info. that we assume were read in before. Common to employ numerical integration in this process (will study later). As part of this process we calculate the matrices needed in stress recovery. We will save those matrices for later. (On today's computers it is faster to recalculate.) }

NINT = {number of integration points to be used}

NEE = NEN \* NSD {size of element stiffness}

**write** (NINT, NEN, LM) {need this info. to control stress recovery process}

**for** p = 1 **to** NEE **do** {zero out stiffness and load vector (for later)}

    FE(p) = 0.0

**for** q = 1 **to** NEE **do**

        KE(p, q) = 0.0

**end** {do}

**end** {do}

**for** INT = 1 **to** NINT **do** {loop over the integration points and add into the appropriate contributions}

B{of INT} = {calc. strain disp. relationship on shape functions N}

S{of INT} = D{of INT} B{of INT}

**write** (S{of INT})

KE = KE + B{of INT}<sup>T</sup> \* S{of INT} \* WEIGHT{of INT}

**end** {do element stiffness}

{Calculate the contribution to the element loads due to body forces and tractions. The contribution due to non-zero essential boundary conditions is handled in ASSEMBLE. Assuming a 2-D case, the contributions can include body forces,  $f_i$ , edge loads,  $h_i$ , and prescribed edge essential BC,  $g_i$ . To simplify the presentation we will assume i) all quantities are uniform in value, ii) there are body forces in both directions, iii) each element edge has two node points, and iv) one edge from node b to c has an edge load in the 2 direction.}

{body force contribution}

**for** a = 1 **to** NEN **do**

**for** i = 1 **to** NSD **do**

p = NSD \*(a-1) + i

$$FE(p) = FE(p) + \int_{\Omega^e} N_a f_i d\Omega$$

**end** {do}

**end** {do}

{edge load contribution - For the specific case given there will be contributions to only two terms in the element load vector}

p = NSD\*(b-1) + 2

$$FE(p) = FE(p) + \int_{\Gamma_{b-c}^e} N_b (b-c) h_2 d\Gamma$$

p = NSD\*(c-1) + 2

$$FE(p) = FE(p) + \int_{\Gamma_{b-c}^e} N_c (b-c) h_2 d\Gamma$$

**end** {ELE\_STIFF}

$$\sigma = DBd^e$$

$$(w, f)$$

$$(w, h)_{\Gamma}$$

**procedure ASSEMBLE (NSD,LM,NEN,KE,FE,G,K,F)**

{procedure to assemble the element contributions into the global matrices. Note in a real program the sparseness of the global matrix would be taken in account and only the terms from the main diagonal up would be considered. Here we use full matrices and add everything.}

**var**

**begin**

p = 0

{the outer loop set is going over rows of stiffness matrix and load vector}

**for** a = 1 **to** NEN **do** {loop over number of nodes in the element}

going over rows of  $k^e$  and  $f^e$

**for** i = 1 **to** NSD **do**

p = p + 1 ← row counter

**if** t of LM(i,a:t) = dof **then** {row is associated with a dof}

{process terms in the row since it a dof}

{if row not associated with a dof – skip row ans go to next row}

P = LM(i,a:t)

F(P) = F(P) + FE(p)

q = 0

{loop set to go over columns of stiffness matrix}

**for** b = 1 **to** NEN **do** {loop over number of nodes in the element}

**for** j = 1 **to** NSD **do**

q = q + 1 ← column counter

**if** t of LM(j,b:t) = dof **then**

{column associated with dof}

Q = LM(j,b:t)

K(P,Q) = K(P,Q) + KE(p,q)

**end** {if}

**if** t of LM(j,b:t) = dog **then**

{column associated with dog}

Q = LM(j,b:t)

F(P) = F(P) - G(Q)\* KE(p,q)

**end** {if}

**end** {do over NSD}

**end** {do over NEN}

**end** {if}

**end** {do over NSD}

**end** {loop over number of nodes in element}

**end** {ASSEMBLE}

**procedure** OUTPUT\_DISP.(NNP,NSD,ID,DISP,G)

{This procedure is responsible for printing the displacements at nodes}

**var**

DISP = {**d**, global displacement vector      ( $n_{dof}$ )}

NNP = { $n_{np}$ , number of nodes mesh}

NSD = { $n_{sd}$ , number of space dimensions}

ID = {"destination structure" holds "global equations numbers"  
explained in SETUP\_EQ}

G = {global prescribed displacement vector      ( $n_{dog}$ )}

DISP\_N = {displacements at one node ( $n_{sd}$ )}

**begin**

**for** A = 1 **to** NNP **do** {loop over the nodes setting the equation or  
prescribed essential BC number and load the global  
nodal loads or prescribed essential BC}

**for** i = 1 **to** NSD **do**

P = ID(i,A:t)

**if** t **of** ID(i,A:t) = *dof* **then** {dof is a dof}

DISP\_N(i) = DISP(P)

**else** {the possible dof is a prescribed essential BC}

**if** t **of** ID(i,A:t) = *dog* **then** {nonzero prescribed  
essential BC}

DISP\_N(i) = G(P)

**else** {zero prescribed essential BC}

DISP\_N(i) = 0.0

**end** {if}

**end** {if}

**end** {loop over dof at node}

**write** (A,DISP\_N(i),i=1,NSD) {write the node's displacements}

**end** {loop over nodes}

**end** {OUTPUT\_DISP.}



**procedure** OUT\_FLUX(NSD, ID, DISP, G)

{This procedure is responsible for calculating and printing the stresses or fluxes}

**var**

DISP = {**d**, global displacement vector ( $n_{dof}$ )}

NSD = { $n_{sd}$ , number of space dimensions}

ID = {"destination structure" holds "global equations numbers" explained in SETUP\_EQ}

G = {**G**, global prescribed displacement vector ( $n_{dog}$ )}

DE = {**d**<sup>e</sup>, element displacement vector ( $n_{ee} = n_{sd}n_{en}$ )}

S = {stress displacement matrix}

SIG = {stress vector - size defined by S matrix}

**begin**

**read** (NINT, NEN, LM) {read info. to control stress recovery process}

{need to get the displacements for the element}

p=0

**for** a = 1 **to** NEN **do** {loop over the nodes in the element}

**for** i = 1 **to** NSD **do**

p=p+1

**if** t **of** LM(i,a:t) = *dof* **then** {dof is a dof}

P = LM(i,a:t)

DE(p) = DISP(P)

**else** {the possible dof is a prescribed essential BC}

**if** t **of** LM(i,a:t) = *dog* **then** {nonzero prescribed essential BC}

P = LM(i,a:t)

DE(p) = G(P)

**else** {zero prescribed essential BC}

DE(p) = 0.0

**end** {if}

**end** {if}

**end** {loop over dof at node}

**end** {loop over number of nodes in the element}

**for** INT = 1 **to** NINT **do** {loop over the integration points and add into the appropriate contributions}

**read** (S{of INT})

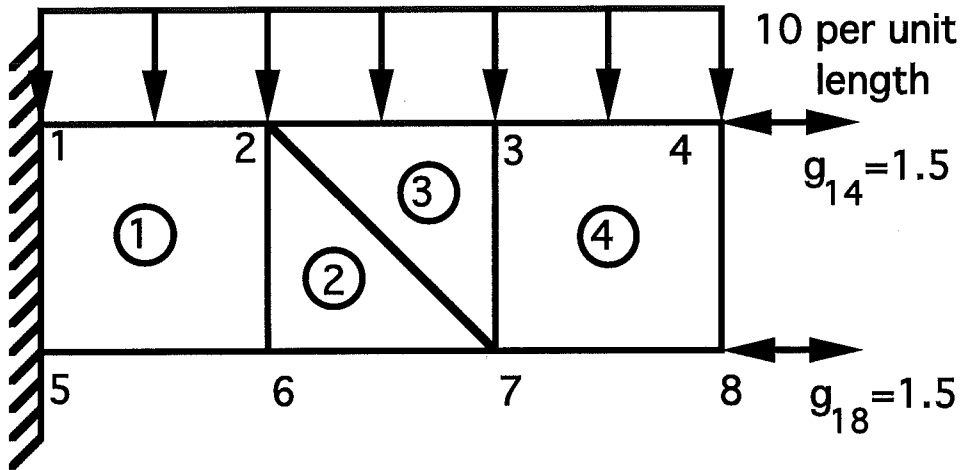
SIG = S \* DE

**write** (SIG)

**end** {for}

**end** {OUTPUT\_FLUX}

## Application of data structure



$$n_{np} = 8, n_{el} = 4, n_{sd} = 2$$

node information

node number	1	2	3	4	5	6	7	8
NTYP	$\begin{Bmatrix} null \\ null \end{Bmatrix}$	$\begin{Bmatrix} dof \\ dof \end{Bmatrix}$	$\begin{Bmatrix} dof \\ dof \end{Bmatrix}$	$\begin{Bmatrix} dog \\ dof \end{Bmatrix}$	$\begin{Bmatrix} null \\ null \end{Bmatrix}$	$\begin{Bmatrix} dof \\ dof \end{Bmatrix}$	$\begin{Bmatrix} dof \\ dof \end{Bmatrix}$	$\begin{Bmatrix} dog \\ dof \end{Bmatrix}$
FG	$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 1.5 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 0 \\ 0 \end{Bmatrix}$	$\begin{Bmatrix} 1.5 \\ 0 \end{Bmatrix}$

ID - Destination Matrix

node →	1	2	3	4	5	6	7	8
i = 1	$\begin{bmatrix} 0: null \end{bmatrix}$	$\begin{bmatrix} 1: dof \end{bmatrix}$	$\begin{bmatrix} 3: dof \end{bmatrix}$	$\begin{bmatrix} 1: dog \end{bmatrix}$	$\begin{bmatrix} 0: null \end{bmatrix}$	$\begin{bmatrix} 6: dof \end{bmatrix}$	$\begin{bmatrix} 8: dof \end{bmatrix}$	$\begin{bmatrix} 2: dog \end{bmatrix}$
i = 2	$\begin{bmatrix} 0: null \end{bmatrix}$	$\begin{bmatrix} 2: dof \end{bmatrix}$	$\begin{bmatrix} 4: dof \end{bmatrix}$	$\begin{bmatrix} 5: dof \end{bmatrix}$	$\begin{bmatrix} 0: null \end{bmatrix}$	$\begin{bmatrix} 7: dof \end{bmatrix}$	$\begin{bmatrix} 9: dof \end{bmatrix}$	$\begin{bmatrix} 10: dof \end{bmatrix}$

$$n_{dof} = 10, n_{dog} = 2$$

element information

element number	1	2	3	4
$n_{en}$	4	3	3	4
IEN	$\begin{Bmatrix} 5 \\ 6 \\ 2 \\ 1 \end{Bmatrix}$	$\begin{Bmatrix} 6 \\ 7 \\ 2 \end{Bmatrix}$	$\begin{Bmatrix} 7 \\ 3 \\ 2 \end{Bmatrix}$	$\begin{Bmatrix} 7 \\ 8 \\ 4 \\ 3 \end{Bmatrix}$

LM - location vectors for elements

element 1

$$\begin{bmatrix} 0: null & 6: dof & 1: dof & 0: null \\ 0: null & 7: dof & 2: dof & 0: null \end{bmatrix}$$

element 2

$$\begin{bmatrix} 6: dof & 8: dof & 1: dof \\ 7: dof & 9: dof & 2: dof \end{bmatrix}$$

element 3

$$\begin{bmatrix} 8: dof & 3: dof & 1: dof \\ 9: dof & 4: dof & 2: dof \end{bmatrix}$$

element 4

$$\begin{bmatrix} 8: dof & 2: dof & 1: dof & 3: dof \\ 9: dof & 10: dof & 5: dof & 4: dof \end{bmatrix}$$

Based on LM consider where terms in element stiffness matrices will be used

element 1

$$\mathbf{k}^1 = \begin{bmatrix} - & - & - & - & - & - & - & - \\ - & - & - & - & - & - & - & - \\ - & - & \mathbf{K}_{6,6} & \mathbf{K}_{6,7} & \mathbf{K}_{6,1} & \mathbf{K}_{6,2} & - & - \\ - & - & \mathbf{K}_{7,6} & \mathbf{K}_{7,7} & \mathbf{K}_{7,1} & \mathbf{K}_{7,2} & - & - \\ - & - & \mathbf{K}_{1,6} & \mathbf{K}_{1,7} & \mathbf{K}_{1,1} & \mathbf{K}_{1,2} & - & - \\ - & - & \mathbf{K}_{2,6} & \mathbf{K}_{2,7} & \mathbf{K}_{2,1} & \mathbf{K}_{2,2} & - & - \\ - & - & - & - & - & - & - & - \\ - & - & - & - & - & - & - & - \end{bmatrix}$$

element 4

$$\mathbf{k}^4 = \begin{bmatrix} \mathbf{K}_{8,8} & \mathbf{K}_{8,9} & \mathbf{F}_8 & \mathbf{K}_{8,10} & \mathbf{F}_8 & \mathbf{K}_{8,5} & \mathbf{K}_{8,3} & \mathbf{K}_{8,4} \\ \mathbf{K}_{9,8} & \mathbf{K}_{9,9} & \mathbf{F}_9 & \mathbf{K}_{9,10} & \mathbf{F}_9 & \mathbf{K}_{9,5} & \mathbf{K}_{9,3} & \mathbf{K}_{9,4} \\ - & - & - & - & - & - & - & - \\ \mathbf{K}_{10,8} & \mathbf{K}_{10,9} & \mathbf{F}_{10} & \mathbf{K}_{10,10} & \mathbf{F}_{10} & \mathbf{K}_{10,5} & \mathbf{K}_{10,3} & \mathbf{K}_{10,4} \\ - & - & - & - & - & - & - & - \\ \mathbf{K}_{5,8} & \mathbf{K}_{5,9} & \mathbf{F}_5 & \mathbf{K}_{5,10} & \mathbf{F}_5 & \mathbf{K}_{5,5} & \mathbf{K}_{5,3} & \mathbf{K}_{5,4} \\ \mathbf{K}_{3,8} & \mathbf{K}_{3,9} & \mathbf{F}_3 & \mathbf{K}_{3,10} & \mathbf{F}_3 & \mathbf{K}_{3,5} & \mathbf{K}_{3,3} & \mathbf{K}_{3,4} \\ \mathbf{K}_{4,8} & \mathbf{K}_{4,9} & \mathbf{F}_4 & \mathbf{K}_{4,10} & \mathbf{F}_4 & \mathbf{K}_{4,5} & \mathbf{K}_{4,3} & \mathbf{K}_{4,4} \end{bmatrix}$$